



# Learning good views through intelligent galleries

Thales Vieira

Alex Bordignon

Adelailson Peixoto

Geovan Tavares

Hélio Lopes

Luiz Velho

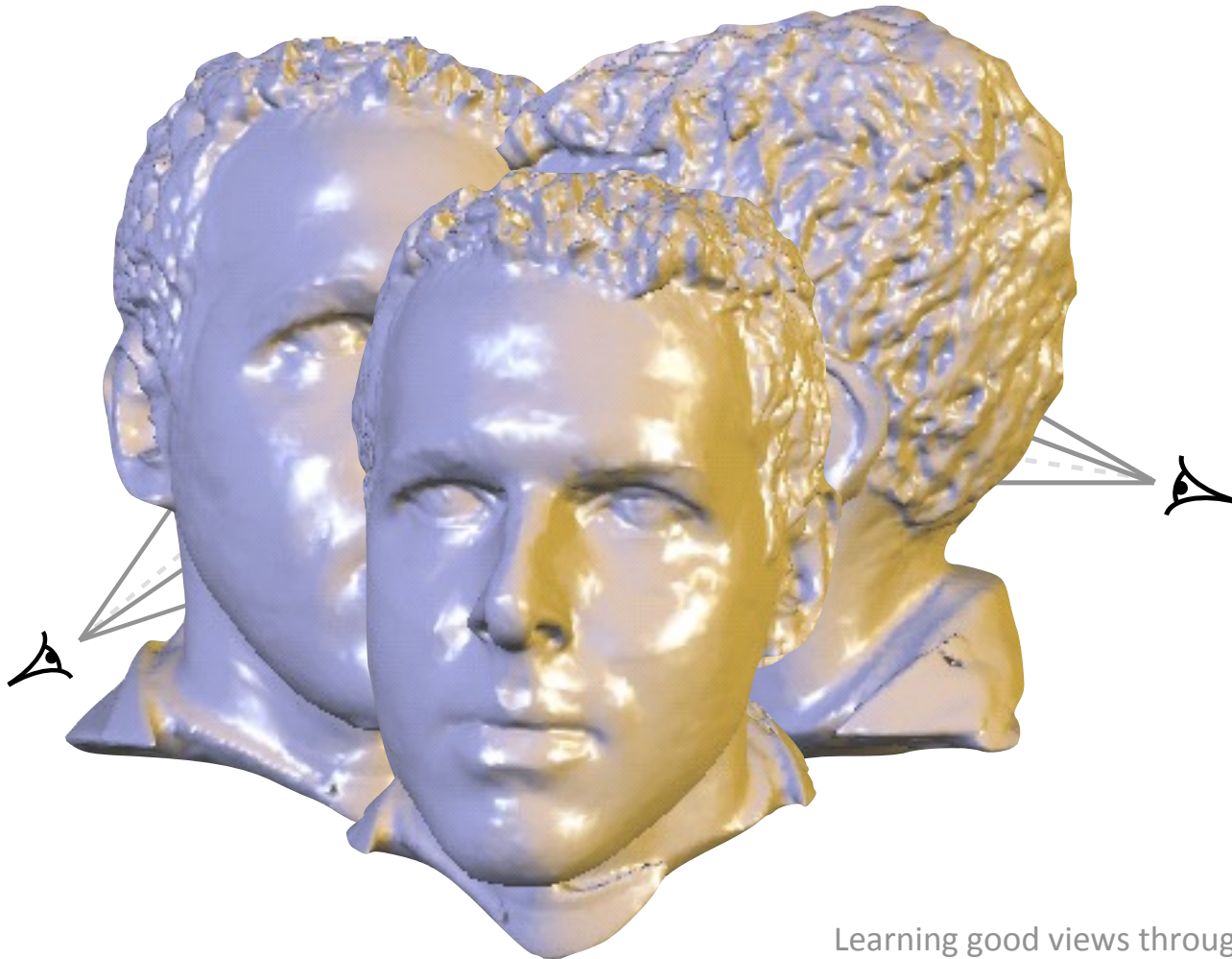
Thomas Lewiner

PUC-Rio de Janeiro

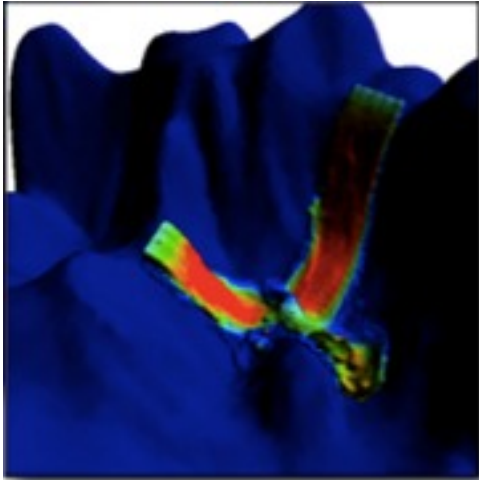
IMPA - Rio de Janeiro

UFAL - Maceió

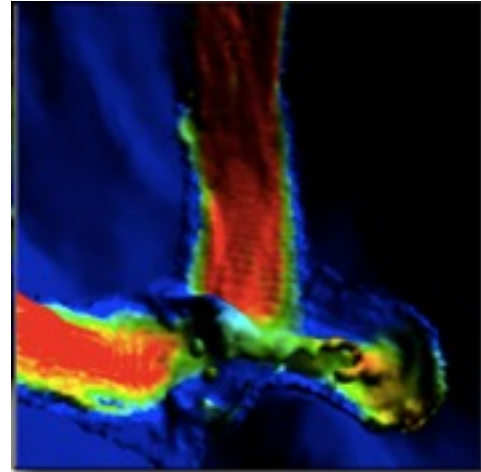
# Camera Placement Problem: Non-linear



# Camera Placement Problem: Subjectivity



Designer Best View



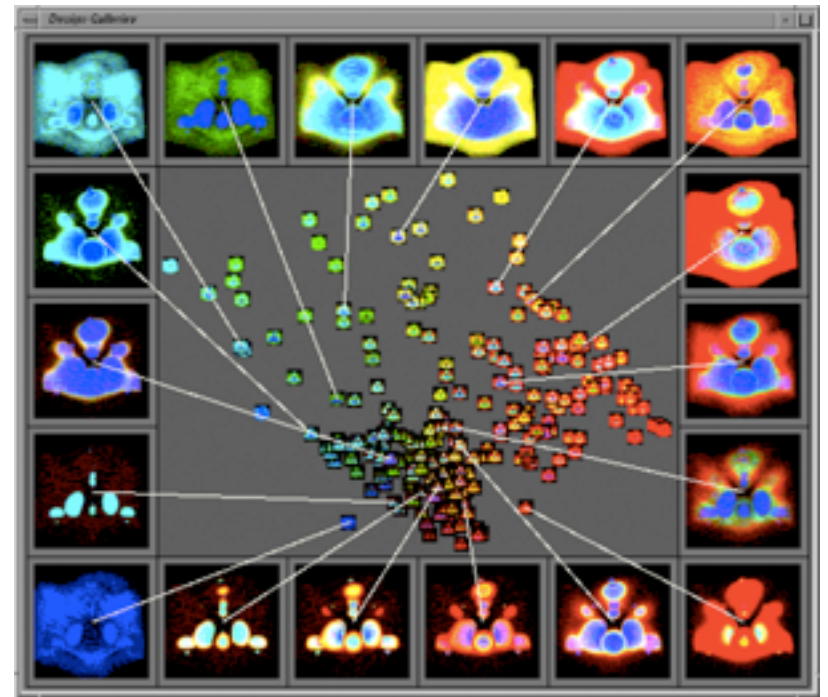
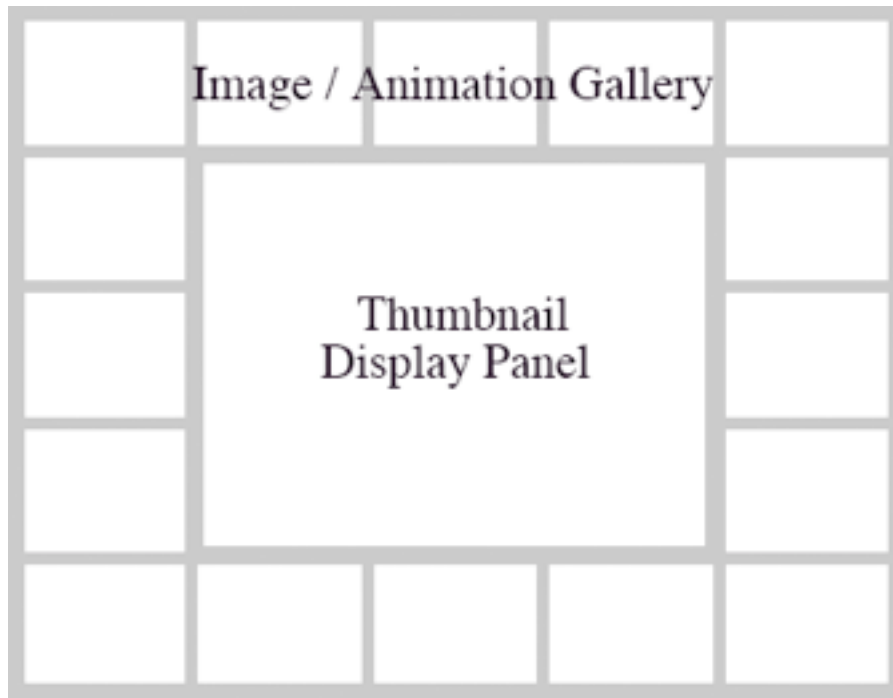
Fluid Specialist Best View

# Our Approach: Learning

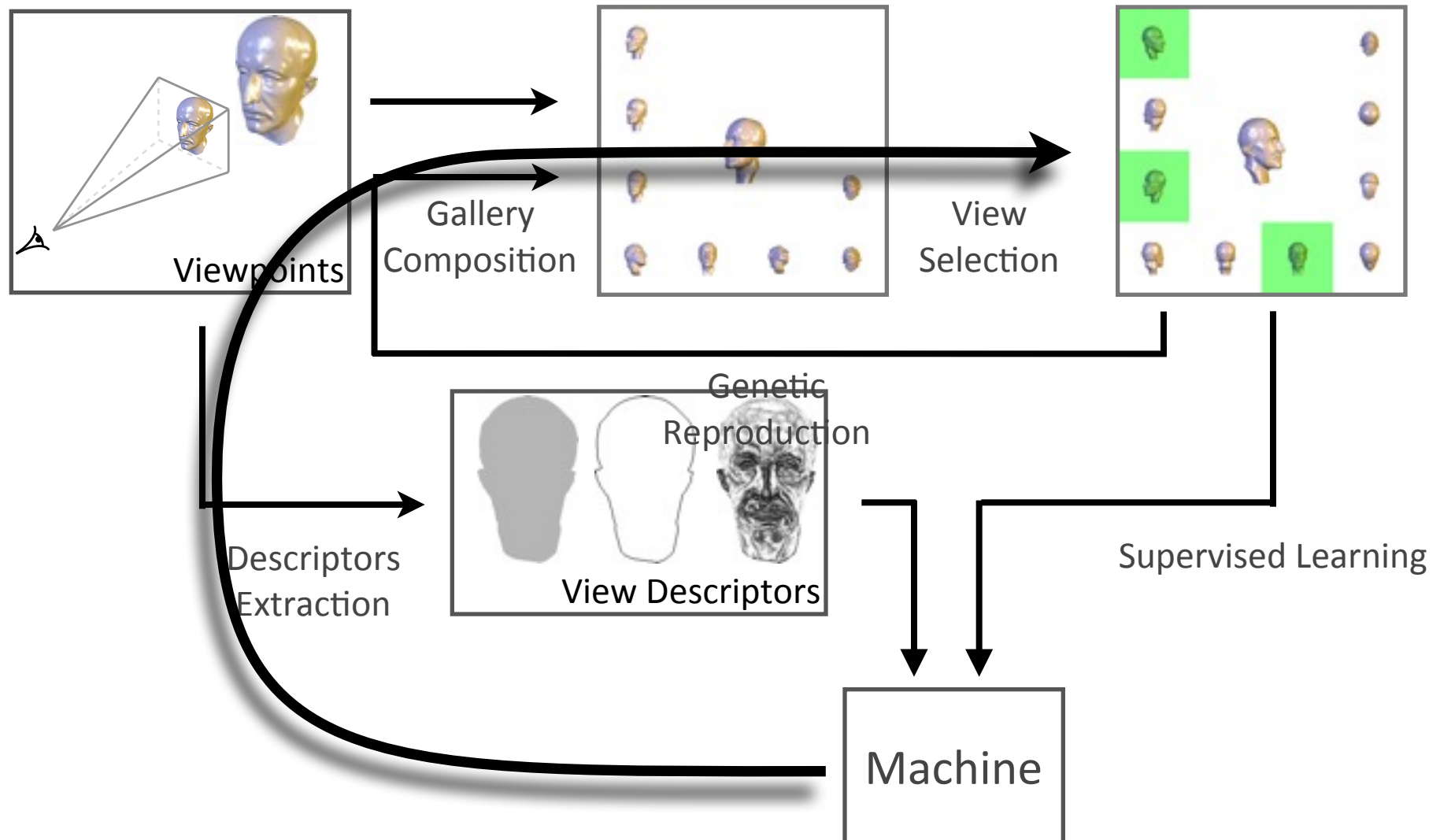


# Exploring multidimensional view space

Design Galleries (*Marks et al., 1997*)



# Learning + Design Galleries = Intelligent Galleries



# Summary

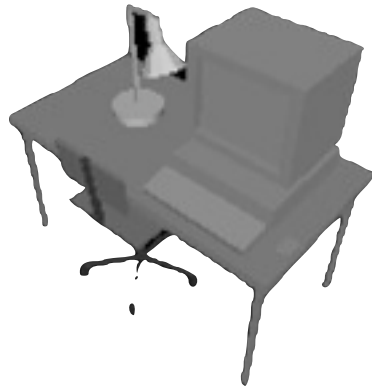
1. Related Work
2. Supervised Learning
3. Intelligent Galleries
4. Results



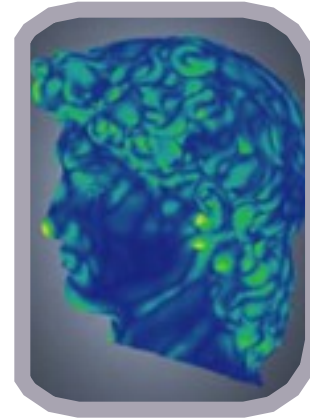


# Related Work

Main trend: Optimize a single criteria



Viewpoint Entropy  
*Vázquez et al (2001)*



Mesh Saliency  
*Lee et al (2005)*



Visibility Ratio



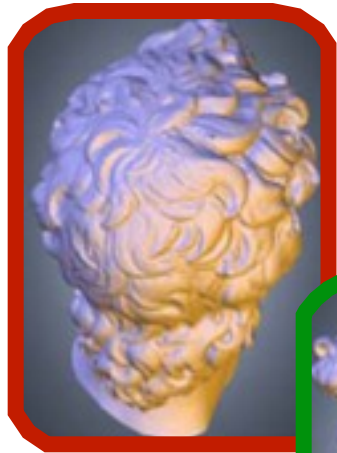
Curvature Entropy  
*Polonsky et al (2005)*



Silhouette length



# Future Work in Previous Work



Curvature



Saliency



Curvature



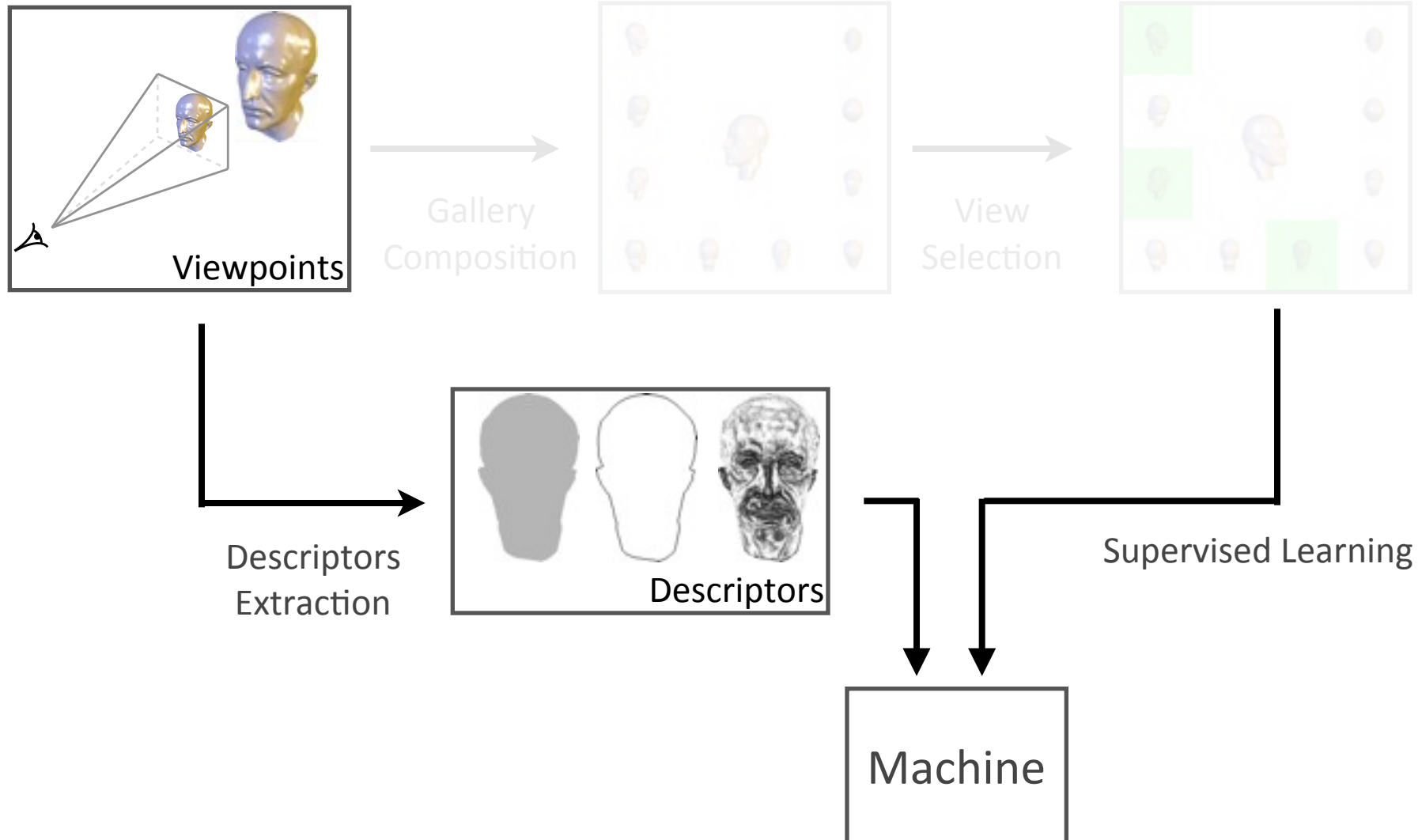
Saliency

*"No one descriptor does a perfect job...."*

*"...since each descriptor does a reasonably good job on a majority of inputs, we are confident that it is possible to combine them to amplify the advantage that each has."*

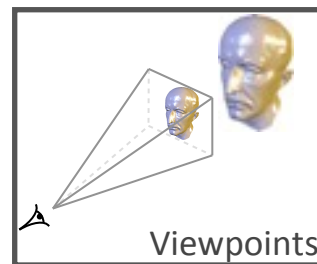
*Polonsky et al. (2005)*

# **Learning** + Design Galleries = Intelligent Galleries



# View Descriptors

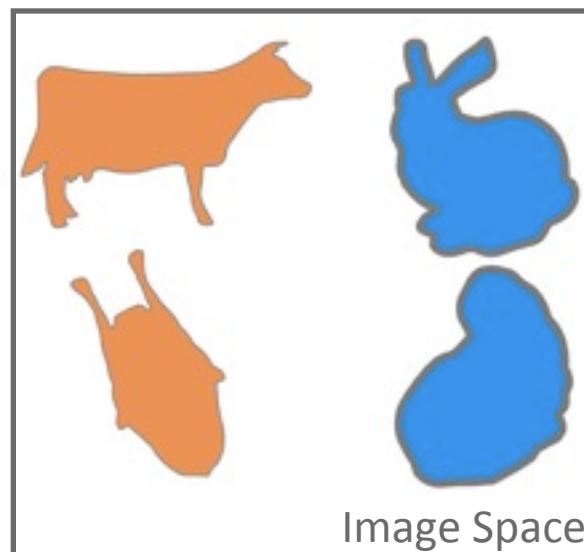
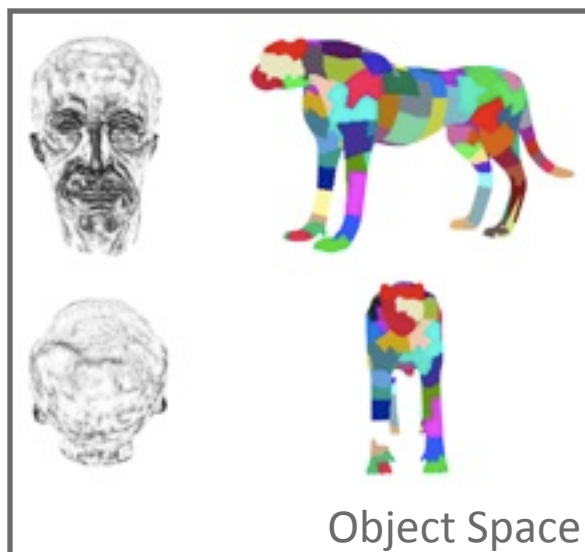
- Mean Curvature
- Visible 3D Surface
- Foreground Alignment
- Silhouette Complexity



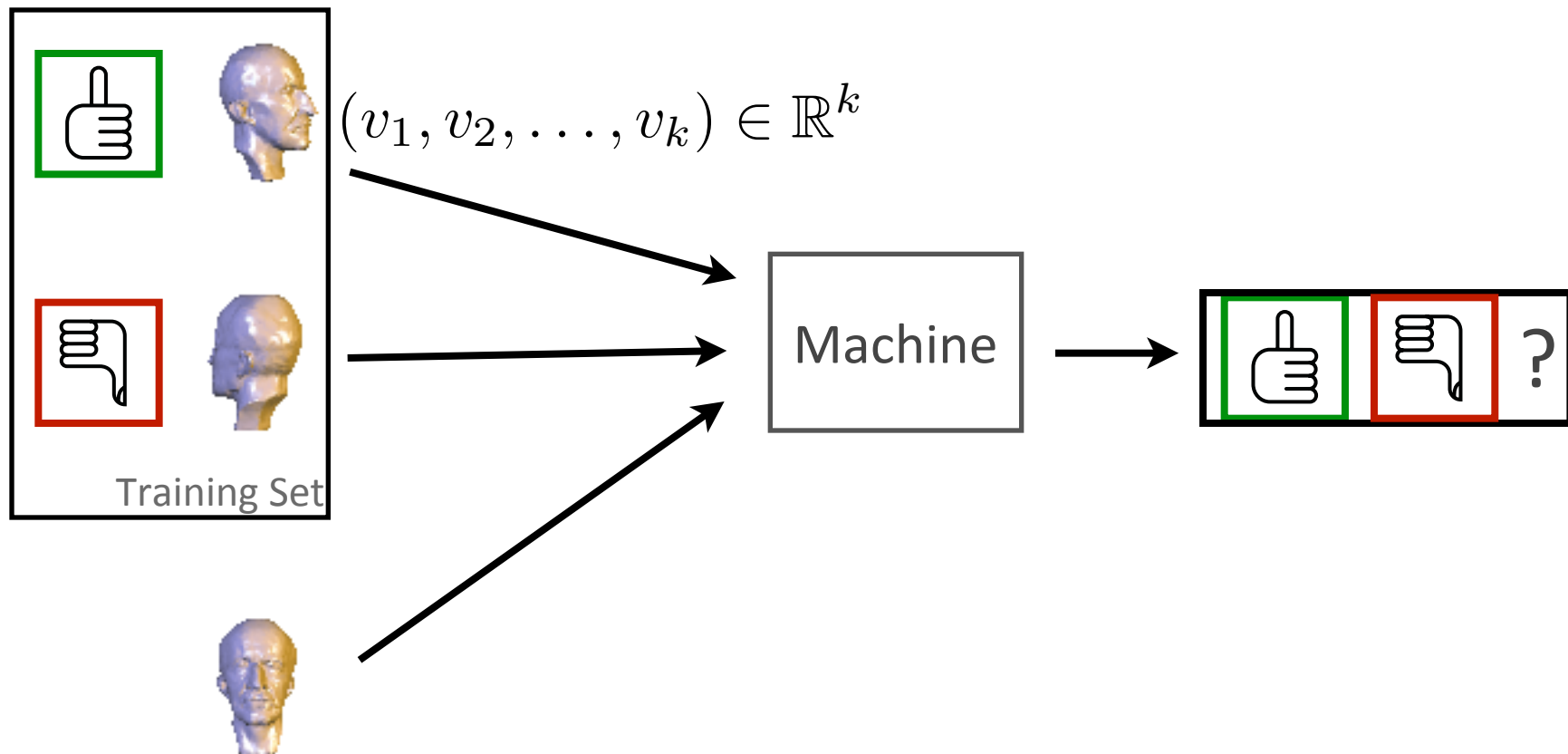
Descriptors  
Extraction



...



# Supervised Learning Machine



# Support Vector Machines (SVM)

Binary classifier

$$\hat{g} : \mathbb{R}^k \rightarrow \{-1, 1\}$$

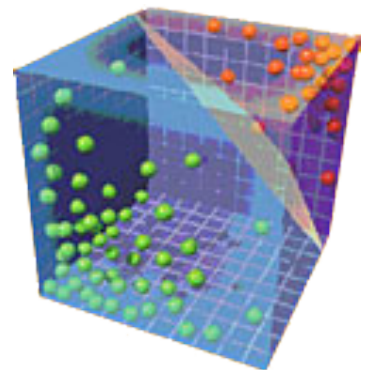
$$v \rightarrow \text{sign} \left( \hat{f}(v) \right) = \{-1, 1\}$$

$$\hat{f}(v) = \sum_j \alpha_j s_j \langle \varphi(v_j), \varphi(v) \rangle + b$$

$$\text{MAX}_{w, \gamma} \quad \gamma - C \sum_{i=1}^l \varepsilon_i$$

$$\text{subject to } y_i \langle w, \Phi(x_i) \rangle \geq \gamma - \varepsilon_i, \quad \varepsilon_i \geq 0, \quad \|w\|^2 = 1$$

- Non-linear classification
- Efficiently computed for small training sets
- Optimal in the sense of VC statistical learning theory



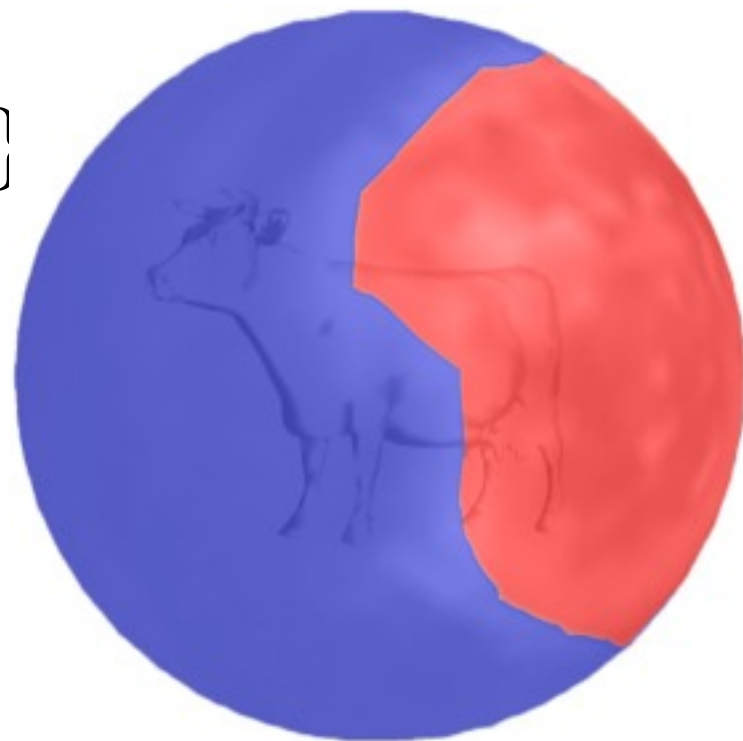
# Ordering views with SVM

SVM binary classifier

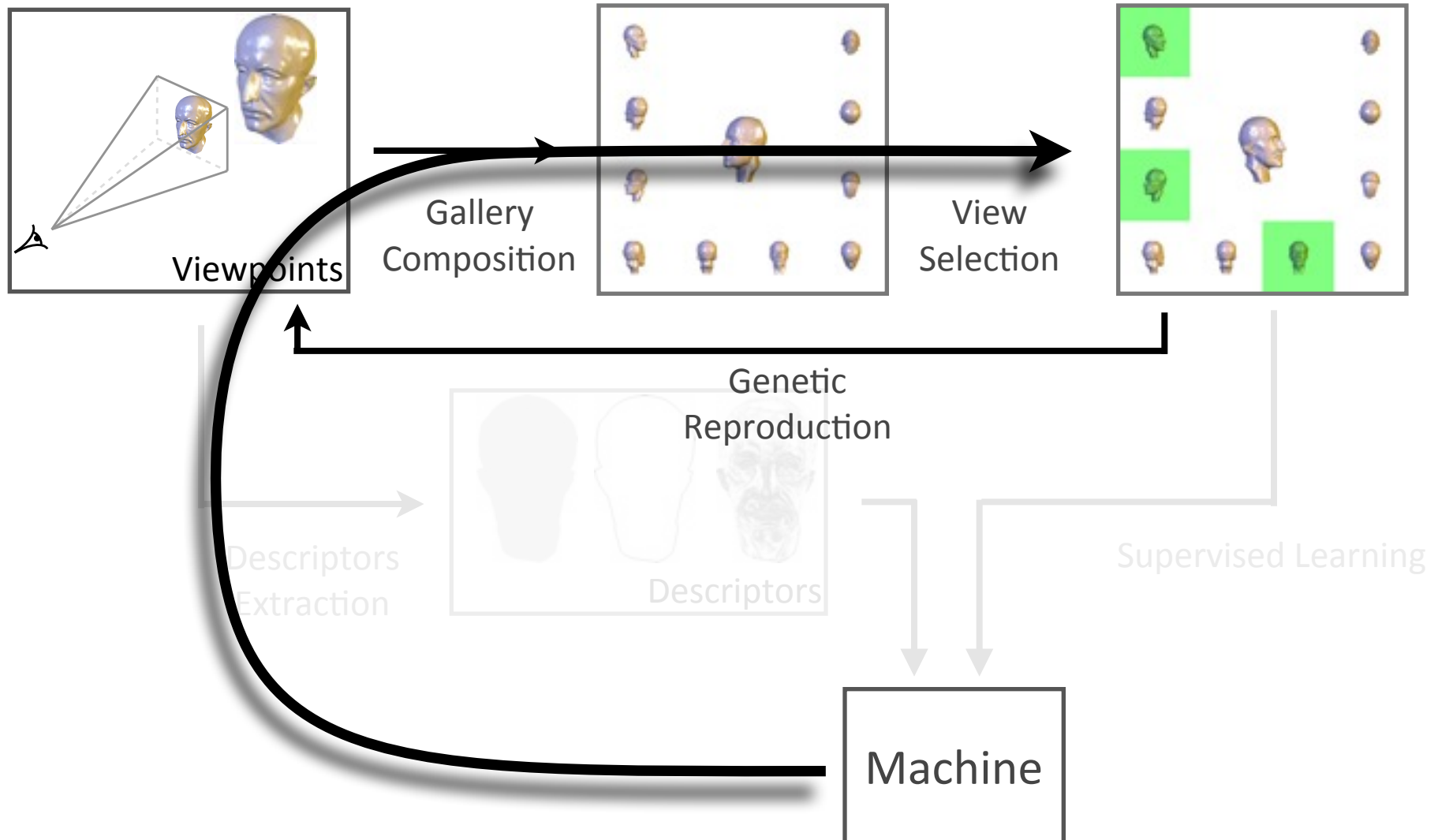
$$v \rightarrow \text{sign} \left( \hat{f}(v) \right) \in \{-1, 1\}$$

SVM adaptation

$$v \rightarrow \hat{f}(v) \in \mathbb{R}$$



# Learning + Design Galleries = Intelligent Galleries





# Intelligent Galleries

*Learning through design galleries*



Automatic  
Selection

Learning good views through intelligent galleries

# Results

# Automatic Selection for Similar Models



# of galleries: 4

Trained view



# Subjectivity

Designer  
Selection



# of galleries: 2

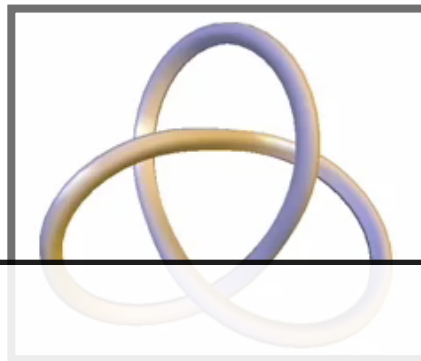
Machine Selection  
from Designer  
Experience

Fluid Specialist  
Selection

# of galleries: 4

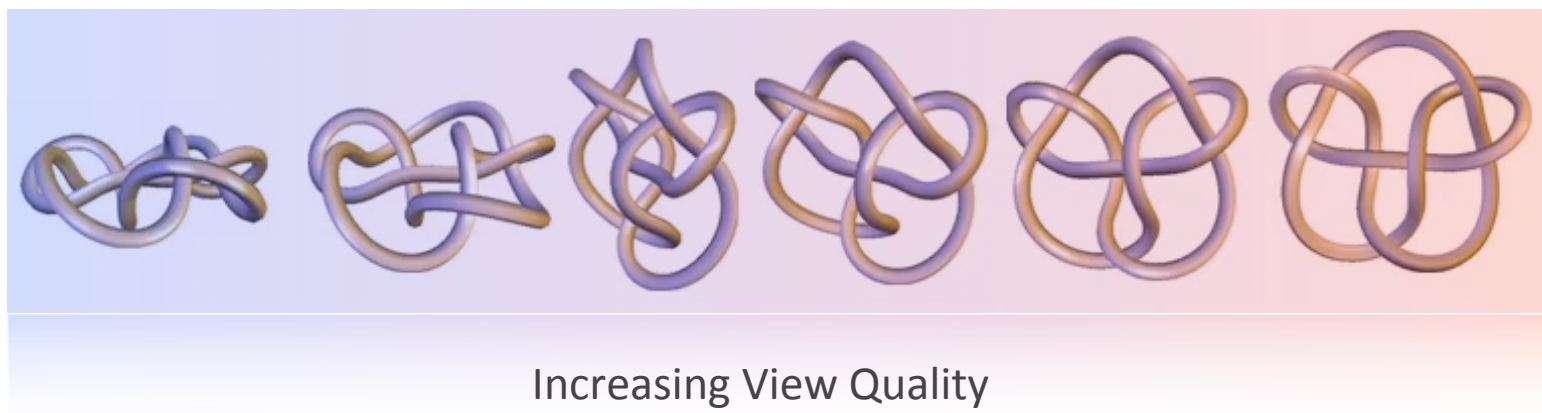
Machine Selection  
from Fluid Specialist  
Experience

# Challenging Scenes: 3D Knots



# of galleries: 2

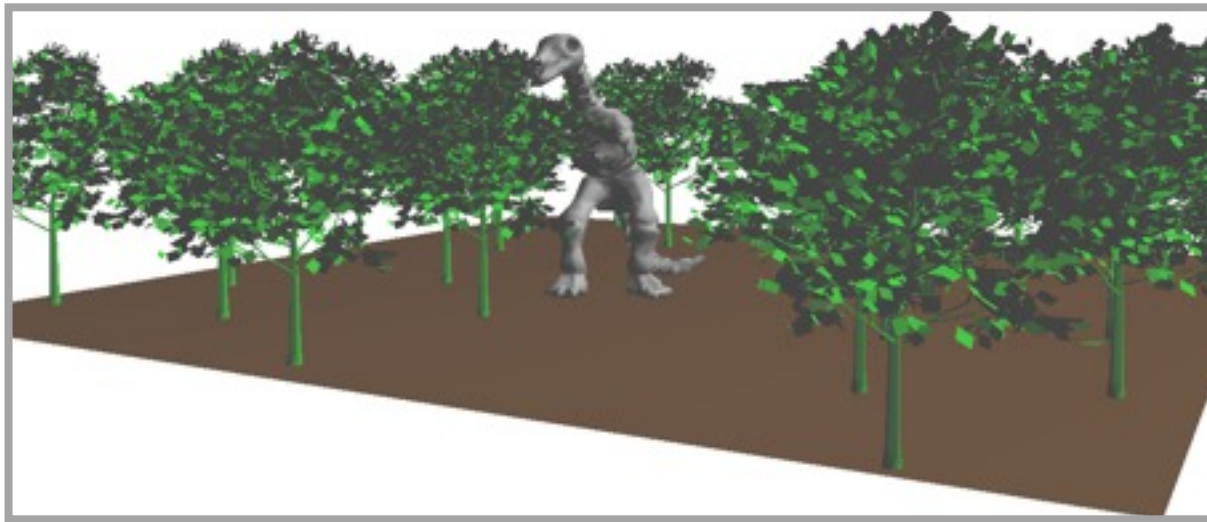
Automatic  
View Classification



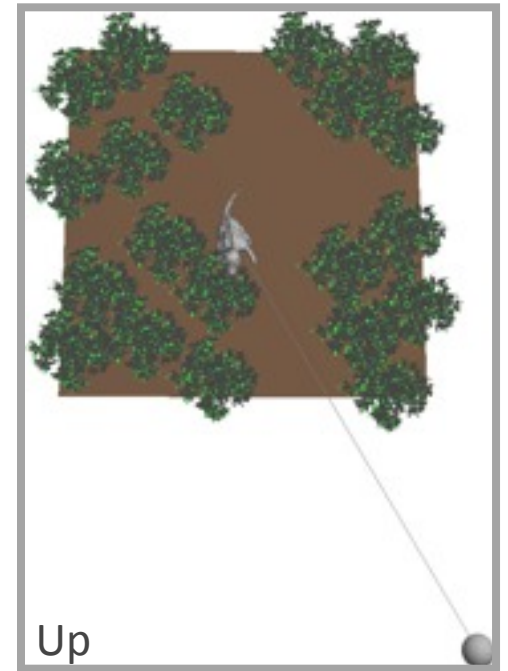
Increasing View Quality

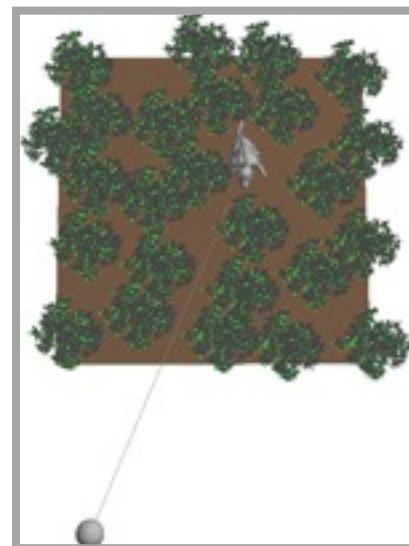
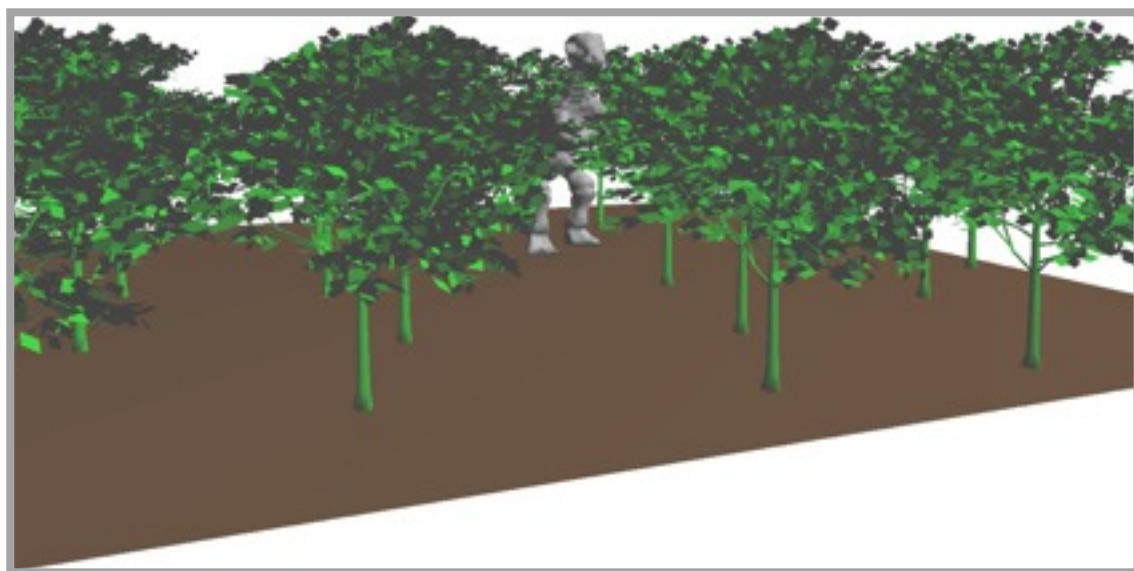
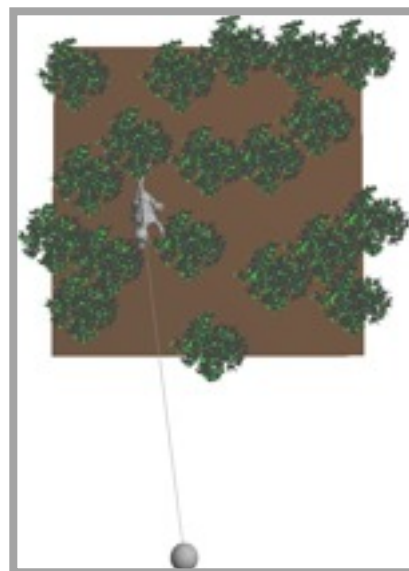
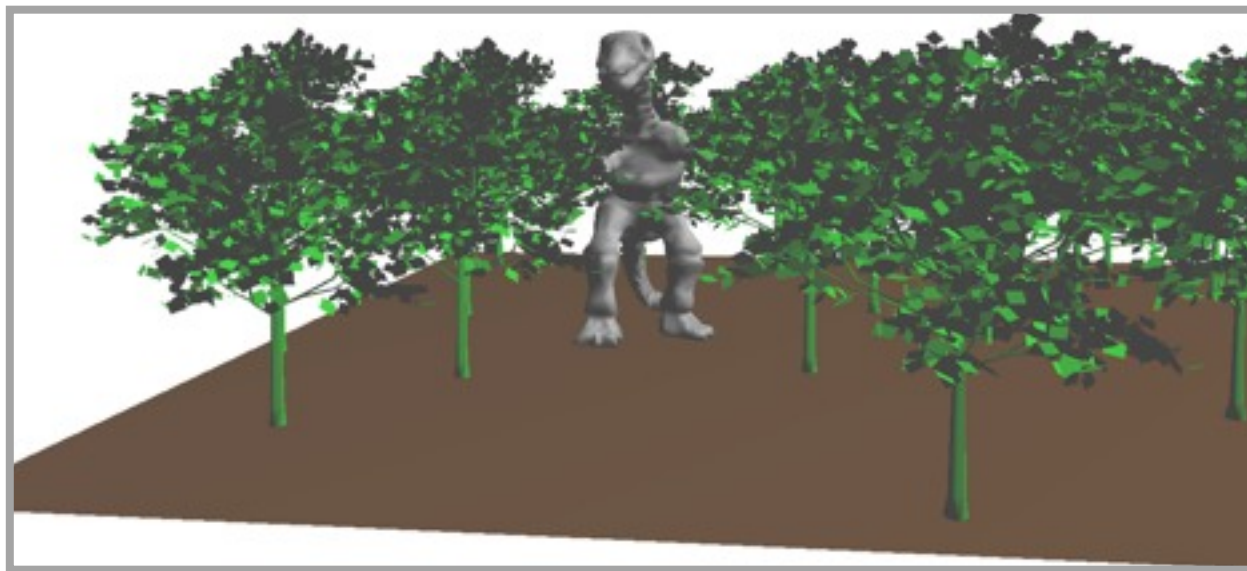


# High Depth / Occlusion Scenes



Trained Best View





Automatically Selected Best Views

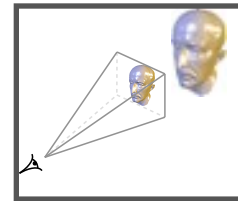


# Timings

- Models Size: 10k~100k triangles
- Average Preprocessing time: 2~4 seconds



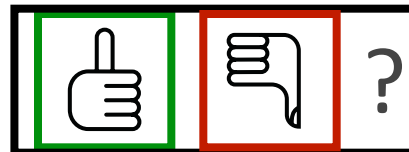
- Average Processing time per view:  
~0.15 seconds



1. Rendering

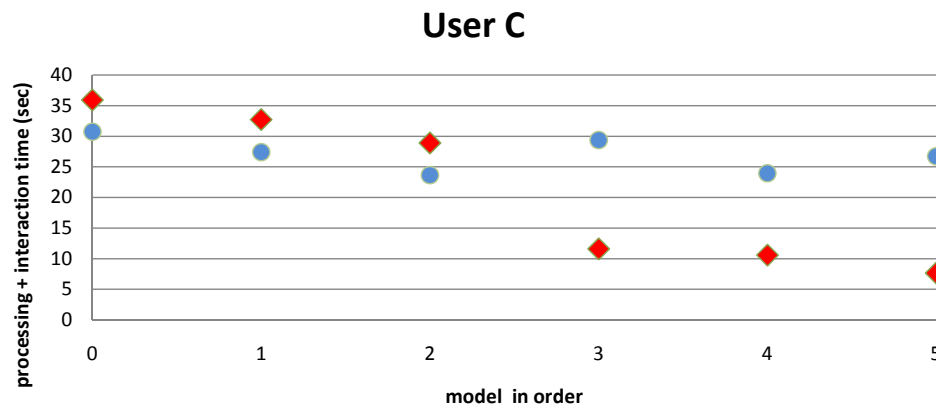
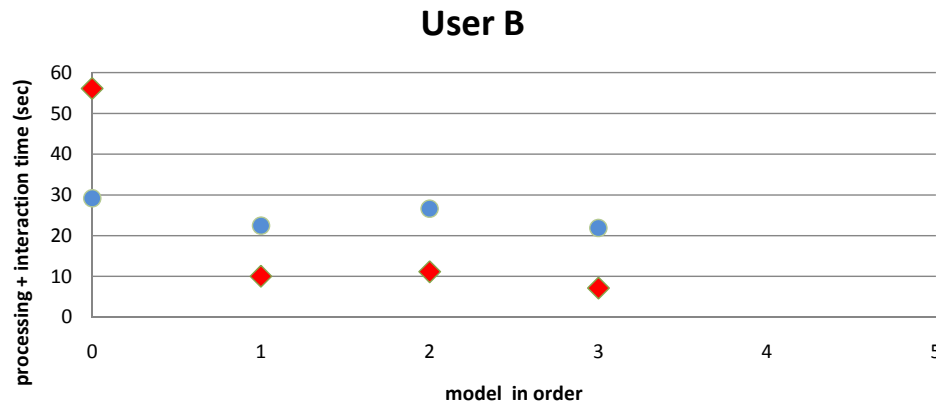
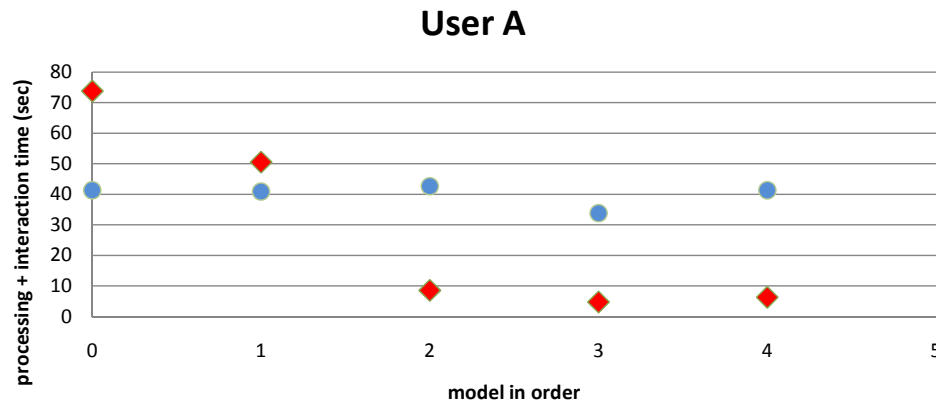


2. View Descriptors  
Extraction



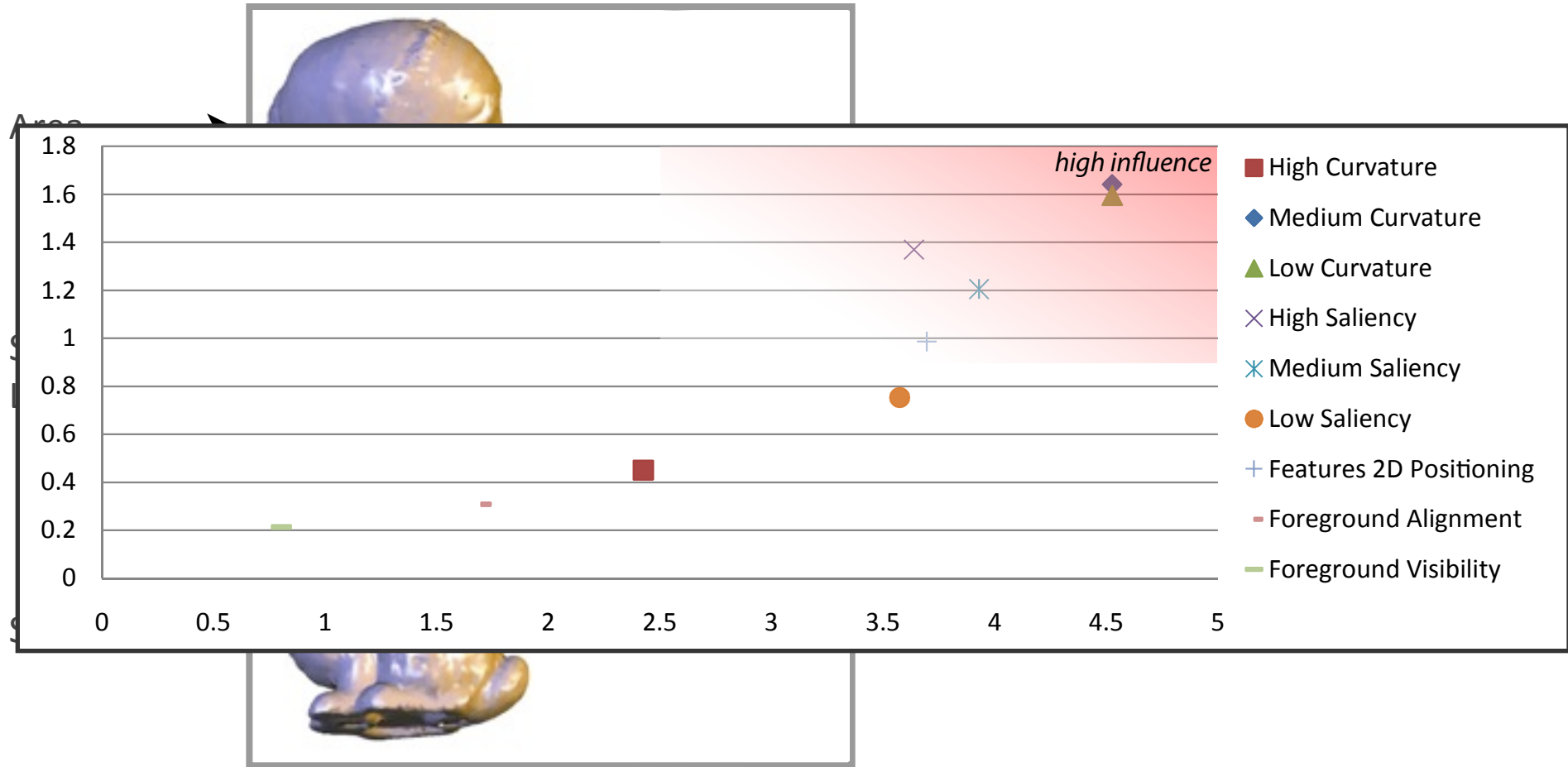
3. SVM Classification

# Learning Curve



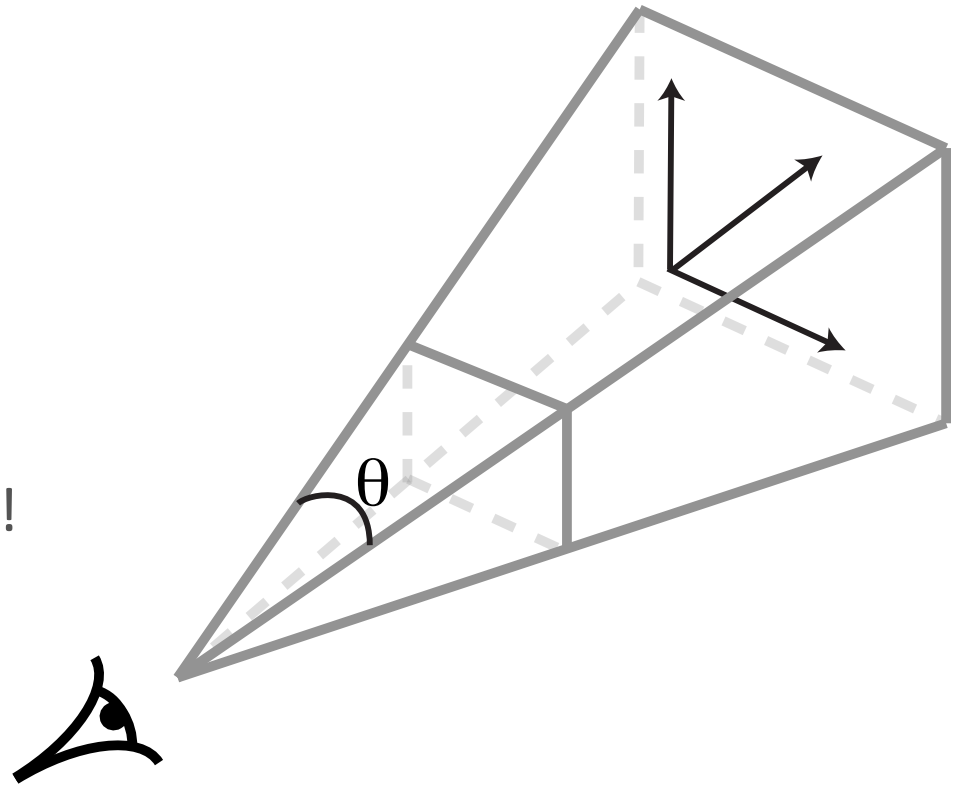
◆ intelligent gallery  
● blender

# Comparison



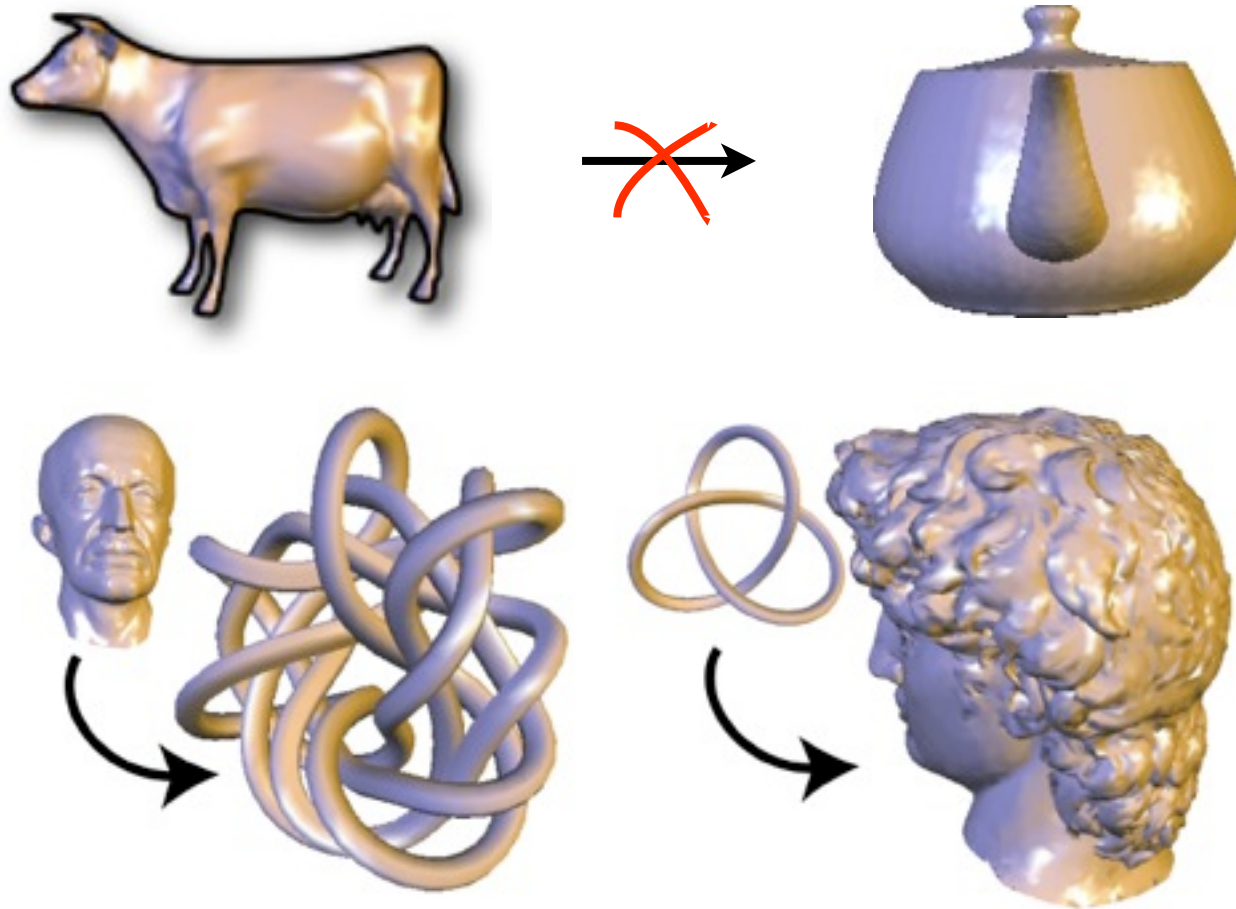
# Limitations: Number of Parameters

1. Position
  2. Direction
  3. Up Vector
  4. Field of View
  5. Near/Far Clipping Plane
- $\Rightarrow k=9 \Rightarrow 512$  initial views!

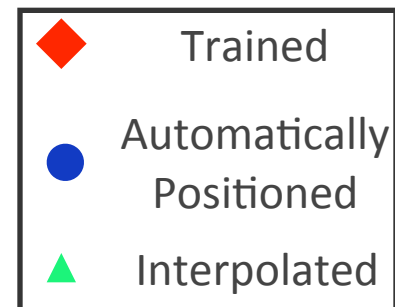
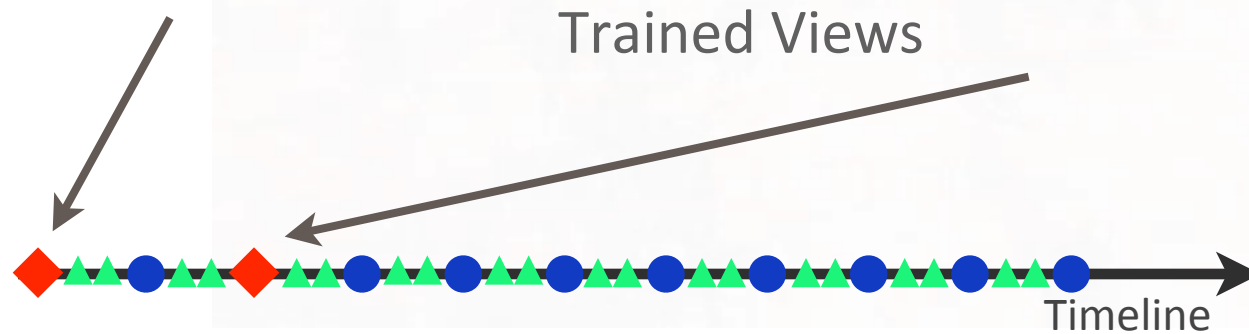
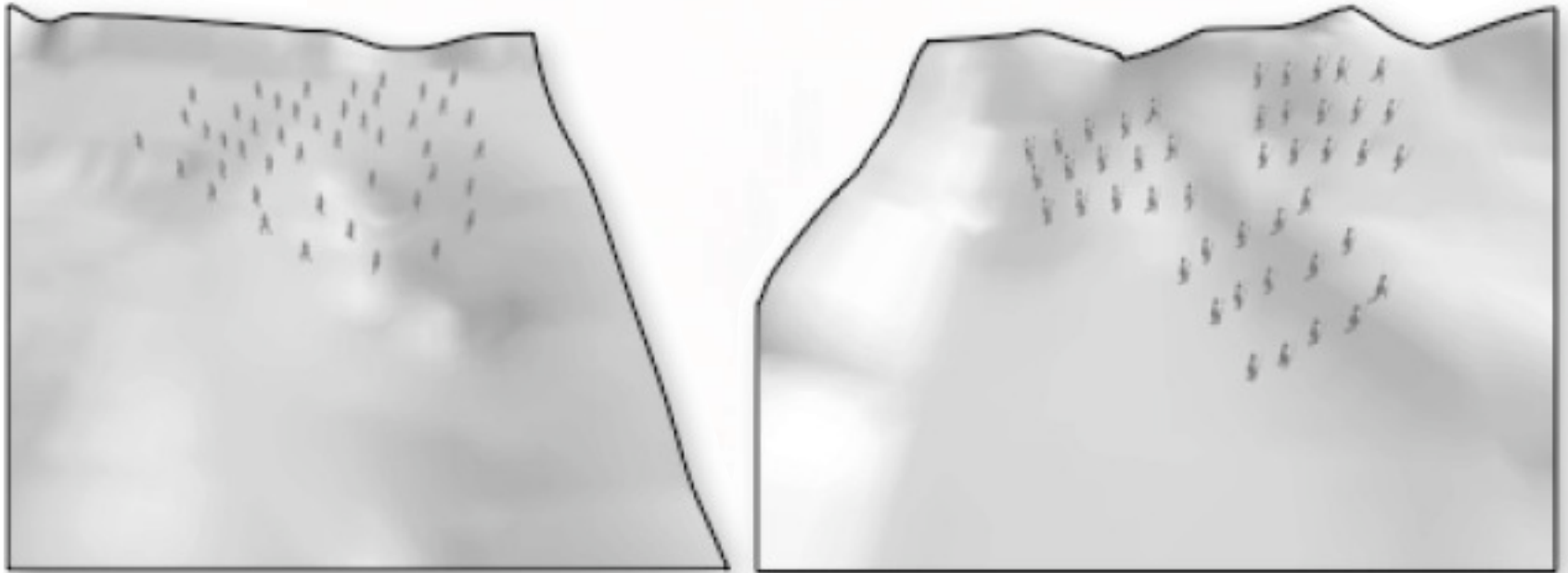


At least  $2^k$  views in the initial gallery!

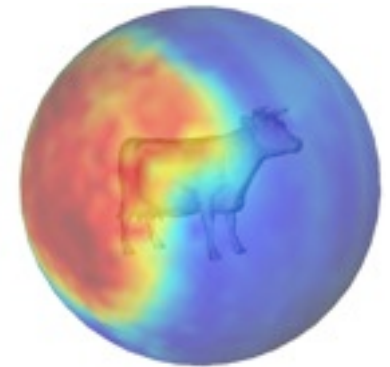
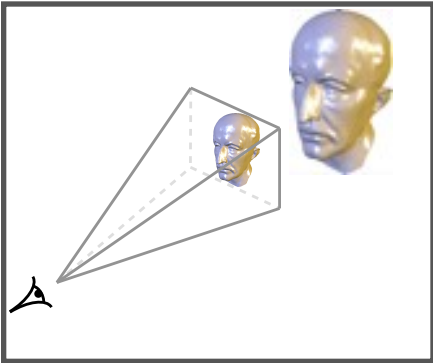
# Similar Objectives Restriction



# Application to 3D Video



# Future Work



- Greater set of descriptors
- Intelligent Galleries for other applications
- Enforce explicit design rules



# Thank you for your attention!

Learning good views through intelligent galleries

Thales Vieira



Thomas Lewiner



Alex Bordignon



Luiz Velho



Adelailson  
Peixoto



Hélio Lopes



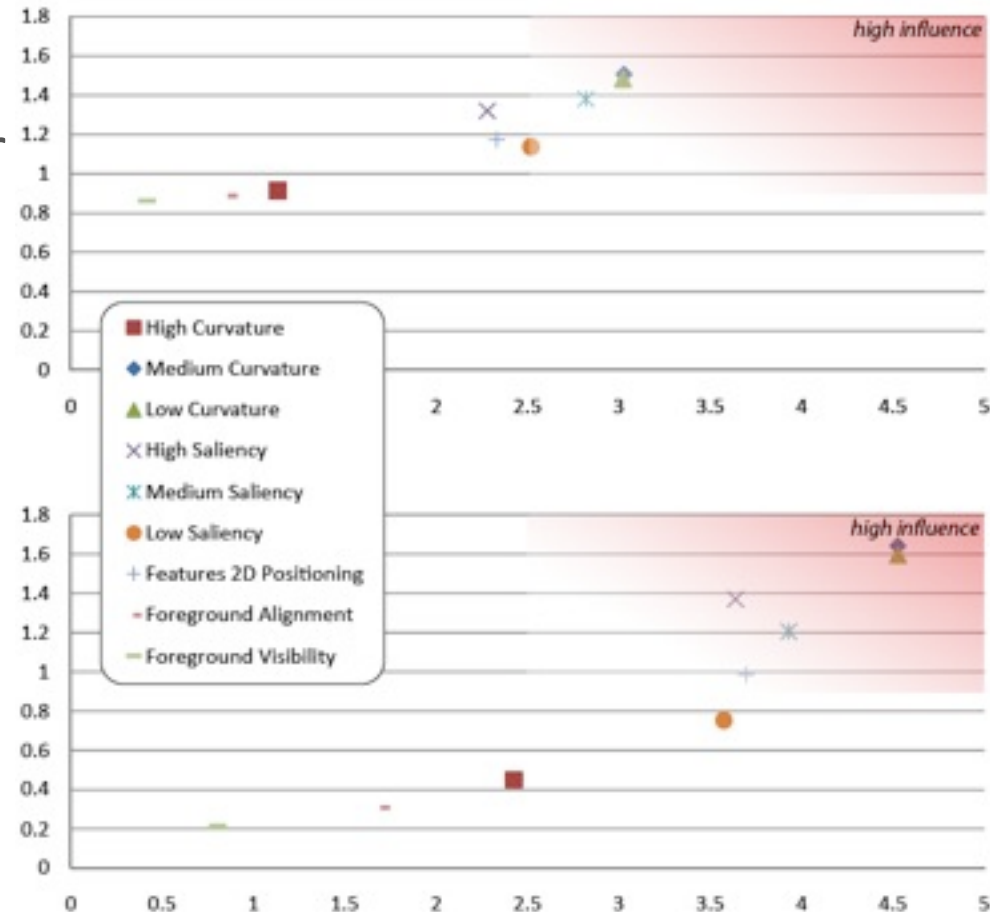
Geovan  
Tavares





# SVM Analysis

- Descriptor Influence:  
Correlation between descriptor values and SVM classification on the training set
- Sigma Optimization:  
Maximization of descriptors influence



# SVM Minimization

$$S = \{(x_i, y_i) ; i = 1, \dots, l\}$$

$$\text{MIN } L(w, S) = \|y - Xw\|^2$$

$$\frac{\partial L(w, S)}{\partial w} = -2X^T y + 2X^T Xw = 0$$

$$(X^T X)w = X^T y \implies w = (X^T X)^{-1} X^T y$$

# Kernels

$$\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}^5$$
$$(x, z) \mapsto (x, z, x^2, z^2, xz)$$

$$K(x, z) = \langle \Phi(x), \Phi(z) \rangle$$

$$K(x, z) = K_1(x, z) + K_2(x, z)$$

$$K(x, z) = cK_1(x, z)$$

$$K(x, z) = K_1(x, z)K_2(x, z)$$

$$K(x, z) = K_1(x, z)^d$$

# Kernels

Linear Kernel:  $K(x, z) = \langle x, z \rangle$

Polynomial Kernel:  $K(x, z) = \sum_{i=1}^l a_i \langle x, z \rangle^i$

Gaussian Kernel:  $K(x, z) = e^{\left(-\frac{\|x-z\|^2}{2\sigma^2}\right)}$

Anova Kernel:  $K(x, z) = \langle \Phi_d(x), \Phi_d(z) \rangle$

$$\Phi_d : x \rightarrow (\Phi_A(x))_{|A|=d}$$

$$\Phi_A(x) = \prod_{i \in A} x_i = x_i A$$

# Kernels

Linear Kernel:  $K(x, z) = \langle x, z \rangle$

Polynomial Kernel:  $K(x, z) = \sum_{i=1}^l a_i \langle x, z \rangle^i$

Gaussian Kernel:  $K(x, z) = e^{\left(-\frac{\|x-z\|^2}{2\sigma^2}\right)}$

Anova Kernel:  $K(x, z) = \langle \Phi_d(x), \Phi_d(z) \rangle$

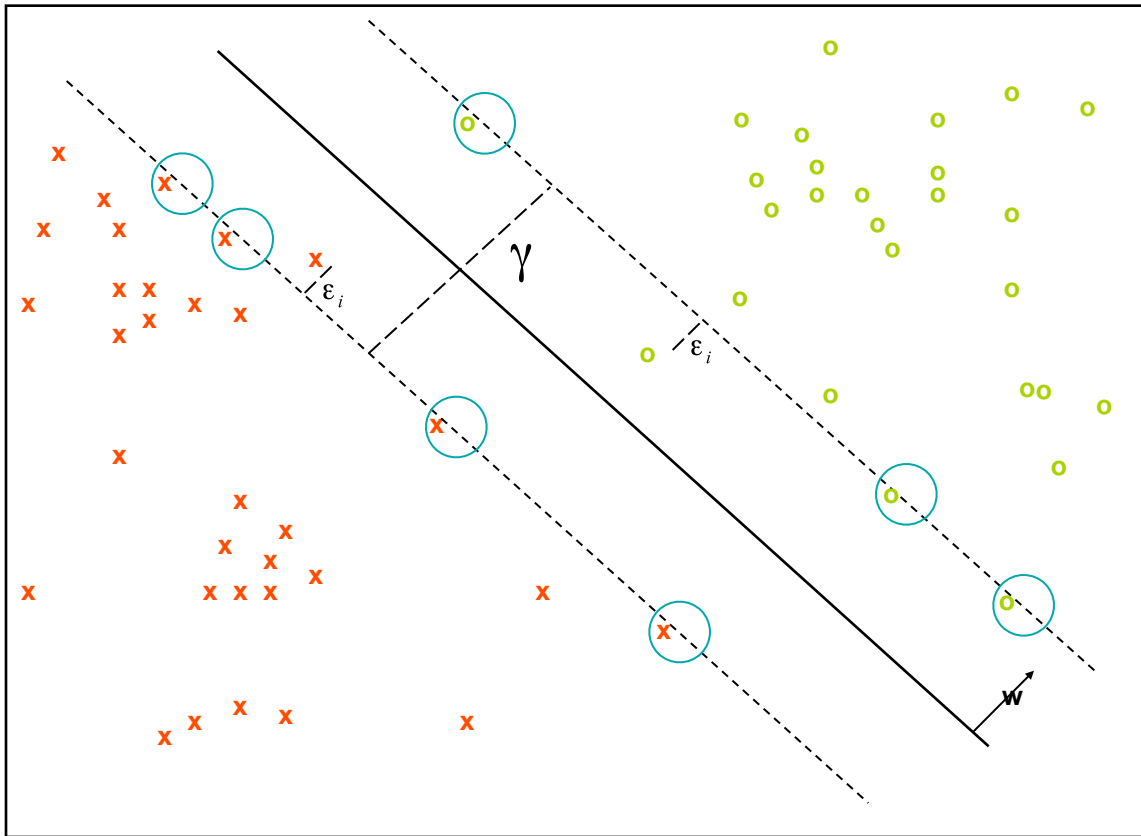
$$\Phi_d : x \rightarrow (\Phi_A(x))_{|A|=d}$$

$$\Phi_A(x) = \prod_{i \in A} x_i = x_i A$$



# SVM

- Convex Optimization (Stability)
- Quadratic Problem (Precision)



# SVM Solution

$$\underset{w, \gamma}{\text{MAX}} \quad \gamma - C \sum_{i=1}^l \varepsilon_i$$

$$\text{subject to } y_i \left\langle w, \Phi(x_i) \right\rangle \underset{i=1, \dots, l}{\geq} \gamma - \varepsilon_i, \quad \varepsilon_i \geq 0, \quad \|w\|^2 = 1$$

$$\alpha_i \left[ y_i \left\langle w^*, \Phi(x_i) \right\rangle - (\gamma - \varepsilon_i) \right] = 0 \quad \rightarrow \quad \alpha_i \neq 0 \quad \forall i \in SV$$