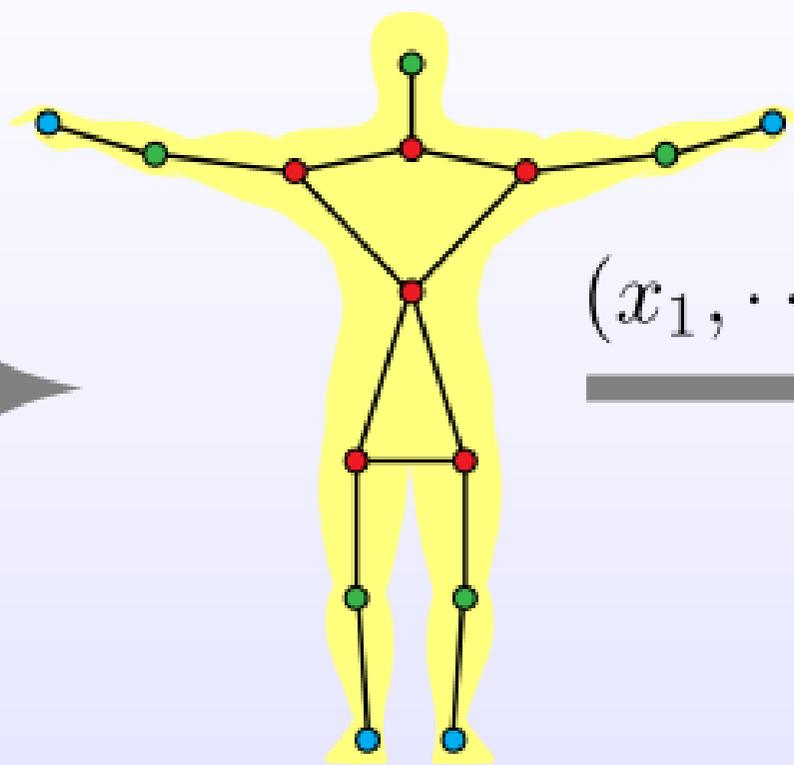


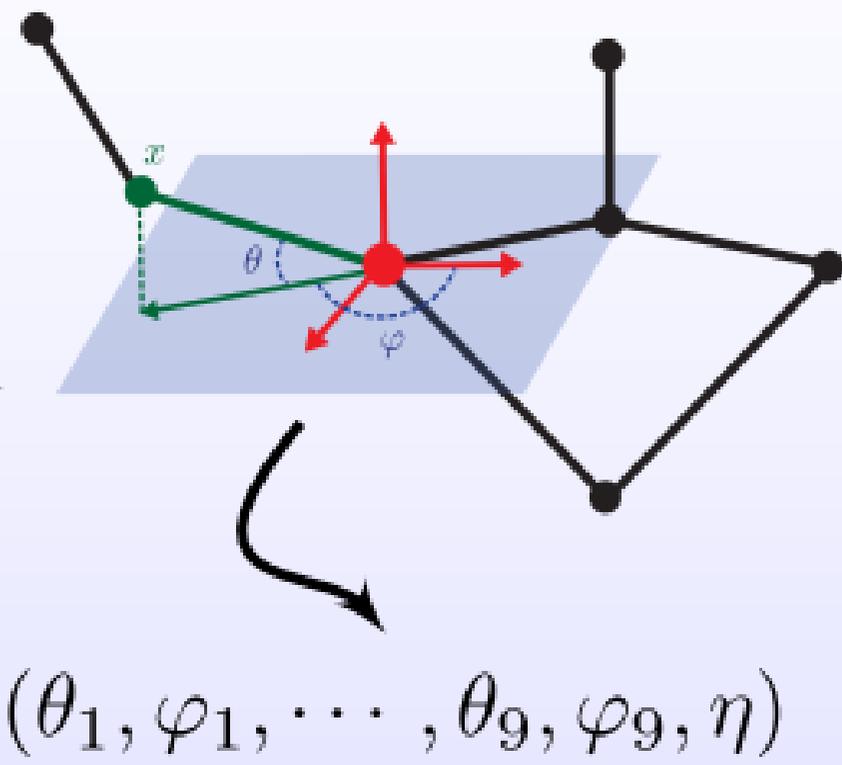
# pose descriptor extraction



kinect



$(x_1, \dots, x_{15})$



$(\theta_1, \varphi_1, \dots, \theta_9, \varphi_9, \eta)$