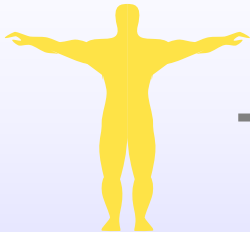
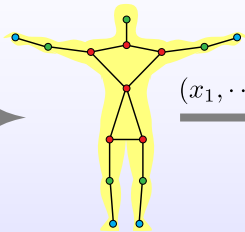


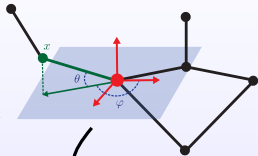
pose descriptor extraction



kinect



(x_1, \dots, x_{15})



$(\theta_1, \varphi_1, \dots, \theta_9, \varphi_9, \eta)$